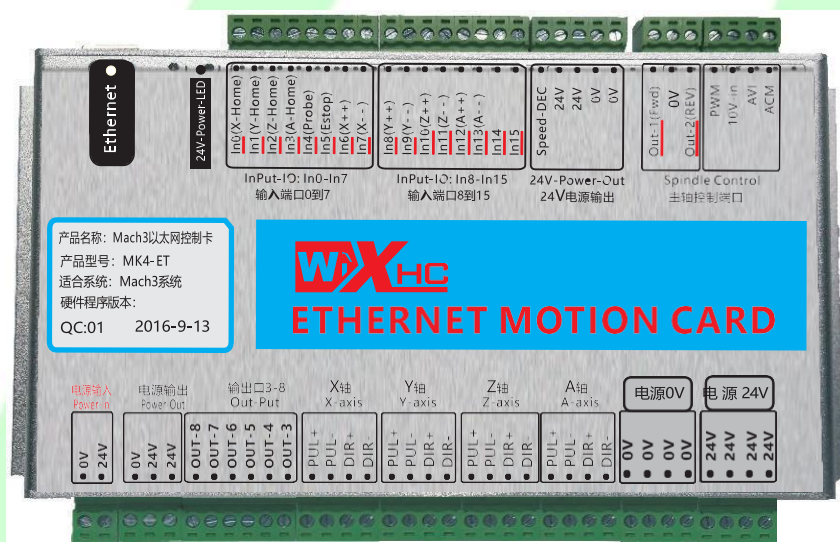




Support CNC System:
Mach3 only

MACH₃ Ethernet Breakout Board

MKX-ET Specification



Product Size : 184x127x30mm

MK₃-ET : 3 Axis Ethernet breakout board

MK₄-ET : 4 Axis Ethernet breakout board

MK₆-ET : 6 Axis Ethernet breakout board



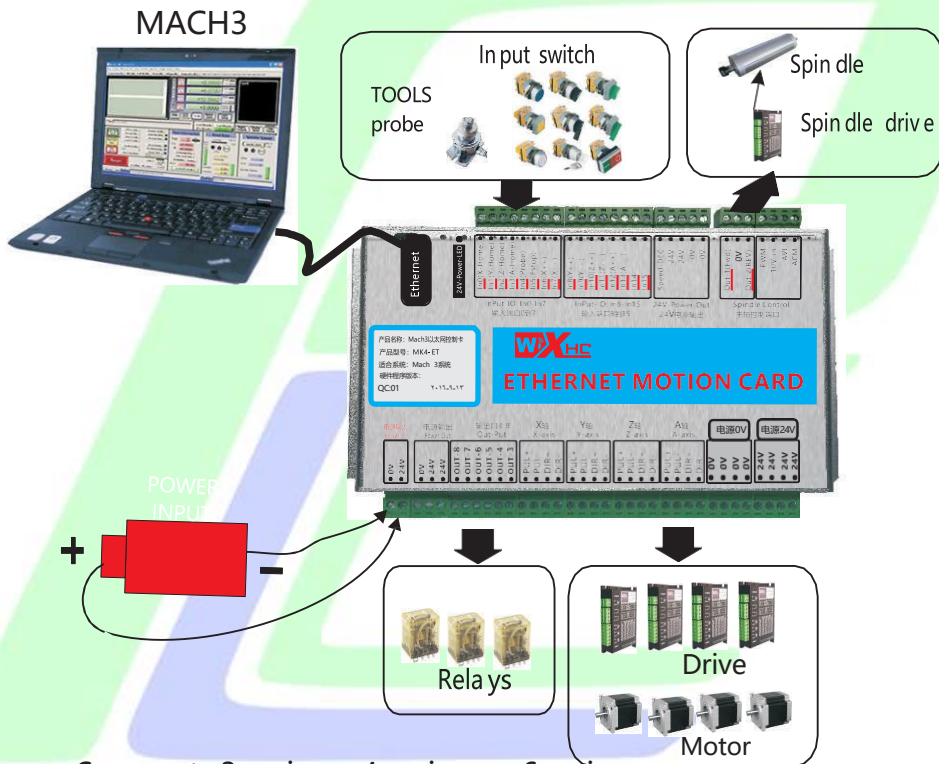
Features:

- ★ Fully supporting all Mach³ versions, support Windows PC,
- ★ Only support Ethernet interface, Need to set IP address
(Please read the last page for reference)
- ★ Support save data when power off
- ★ Support spindle speed feedback
- ★ Support 10 meters Ethernet interface cable
- ★ Supports Up 6-axis
- ★ Maximum step-pulse frequency is 2000KHz
16 general-purpose input, 8 output
- ★ Velocity feedback function, Spindle speed display in real time
- ★ all IO-port isolation, interference, stable performance
- ★ Support servo motor and step motor

Simple connection description

Application Connection Diagram

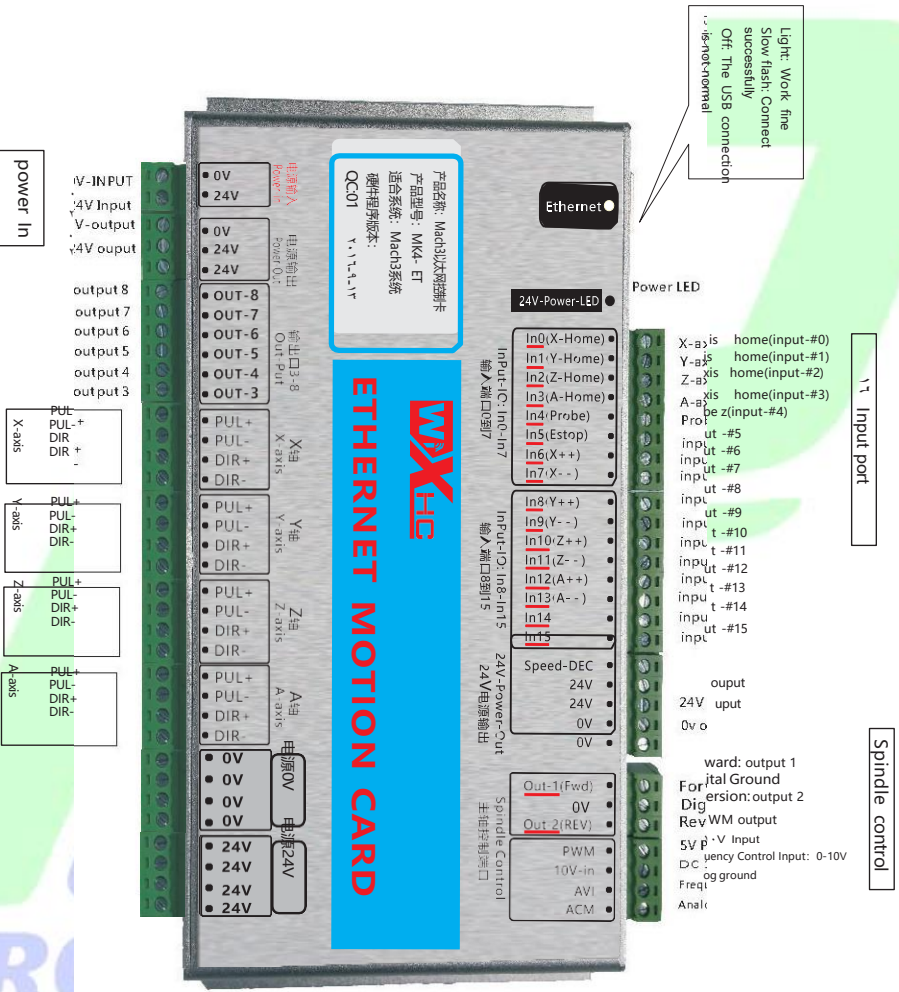
Ethernet Motion Control Card Application



Support: 3-axis or 4-axis, or 6-axis

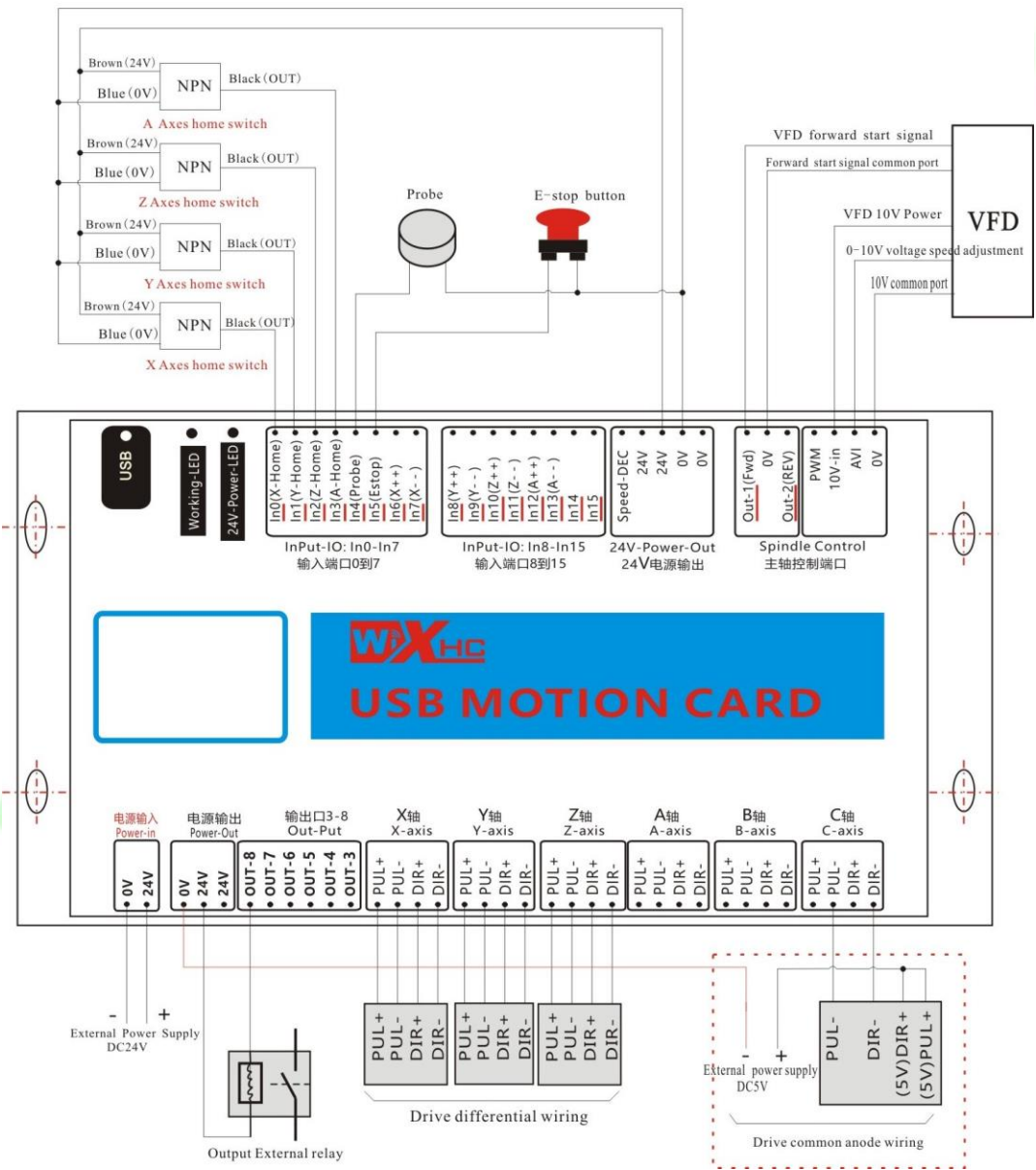
Mk3-ET: 3-axis; Mk4-ET: 4-axis; Mk6-ET: 6-axis

Signal Description



Wiring diagram shows

NOTE: If the inverter is turned on, the control card is not working properly because of interference caused by the inverter; Replace inverter.



Electrical Characteristics

	Parameter Description	
axis output control:	Drive Current	Isolated open collector output; 0V, 20mA
	Drive	Pulse + direction output
	Output frequency	2000KHZ
	axes	MK2-ET:2-axis;MK3-ET:3-axis;MK6-ET:6-axis
	Isolation Voltage	30KV
Spindle inverter output: 3 types of output modes	Analog voltage output	0-10V
	PWM output	0V, 1KHZ,Duty;0-100%
	Pulse+direction output	0V, 10HZ to 1KHZ
4 IO output	Drive Current	Isolation:00mA, 20V
	Isolation Voltage	30KV
16 IO input	Input Current	Isolated inputs, 0 mA, maximum voltage 20V
	Isolation Voltage	30KV

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Software installation

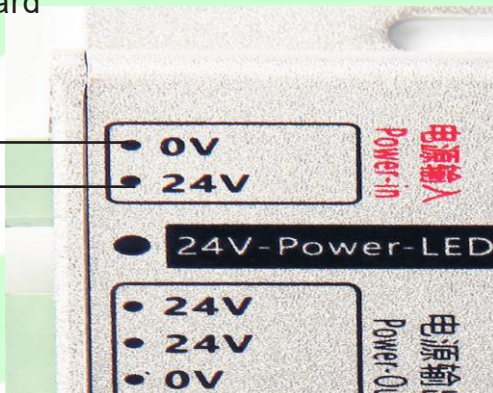
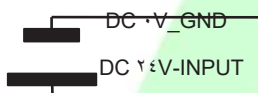
- First, Install Mach3 software to your PC.
- Second, copy our driver files into mach3:
 - 1. Copy the driver file NcEther.dll in Plugins folder to Mach3 plugins folder (C:\Mach3\Plugins)
 - 2. Copy the configuration file Mach3Mill.xml to the Mach3 folder of disk C (C:\Mach3)
 - 3. Copy all m codes, such as M930, m999, etc., from macros folder into Mach3 macros folder (C:\Mach3\macros)
- Check our wiring for reference, connect our card to your machine correctly
- Connect your PC to our card by using network cable
- After these steps, you can open your Mach3 software for operating



Please take a look at mach3 software parameters setting, Step per and so on in the printed manual of our packing box for reference.

1. Offer power supply to our card

DC24V,0.5A

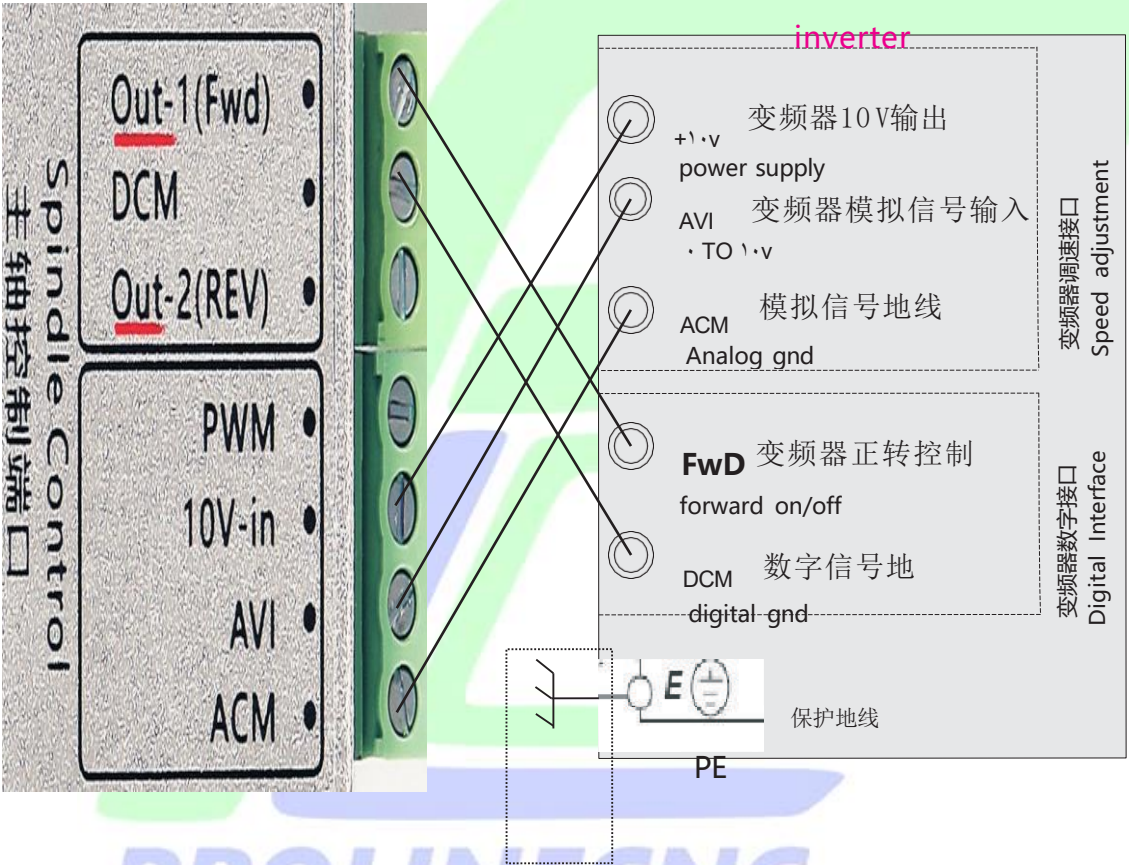


2. Drive connection.

Our card support Servo or stepper drive, Differential output signal

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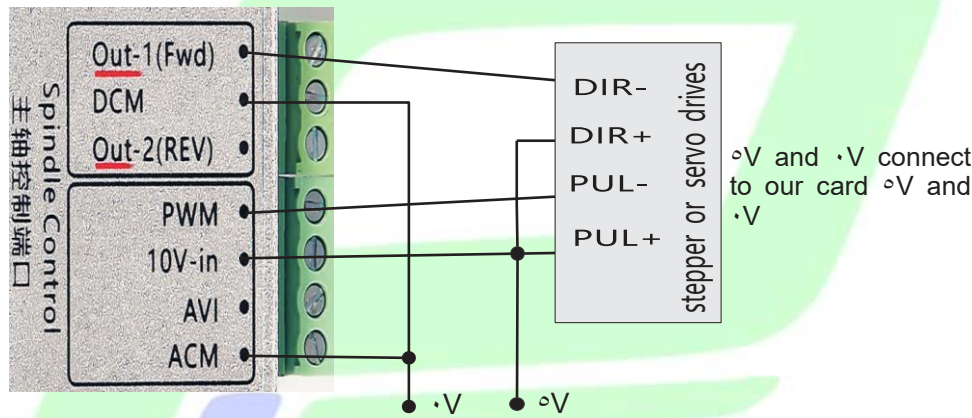
NO.3: Inverter wiring for reference



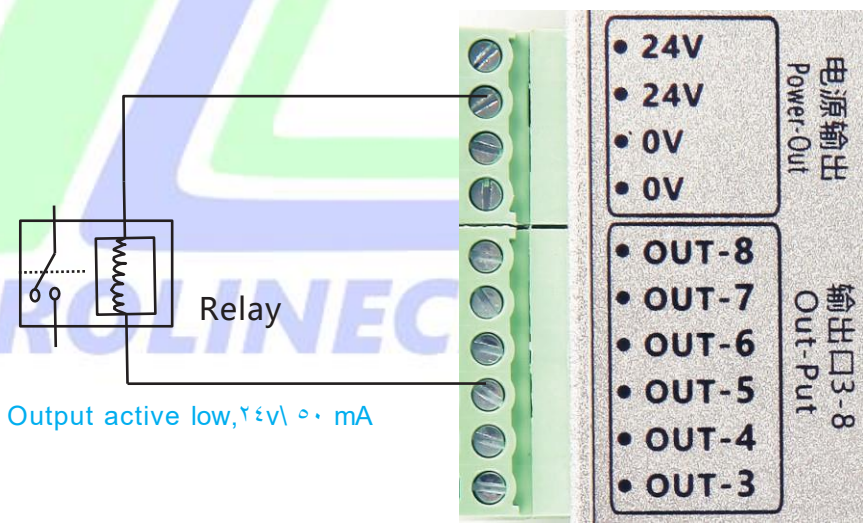
Connected to the machine housing

MKX Wiring

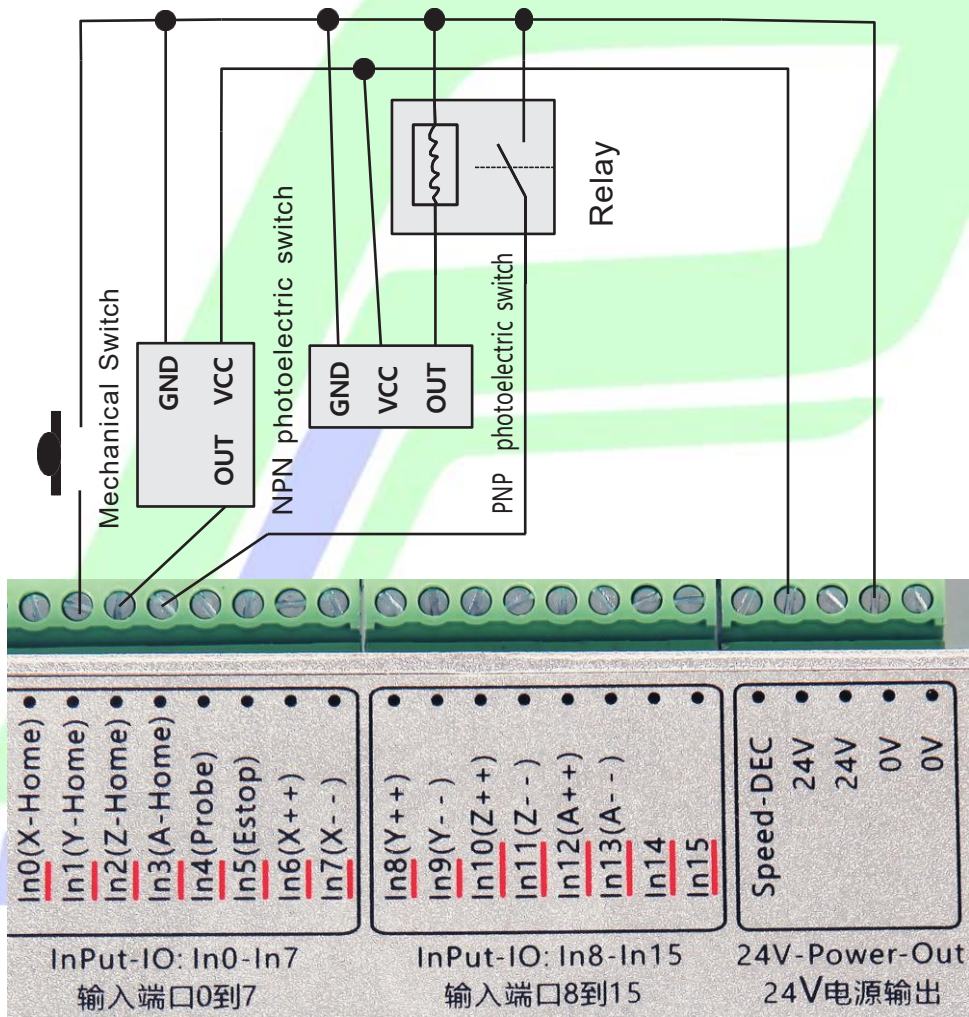
Spindle connected stepper or servo drives



NO.4: Output Relay Interface: OUT1 to OUT8 Relay Interface



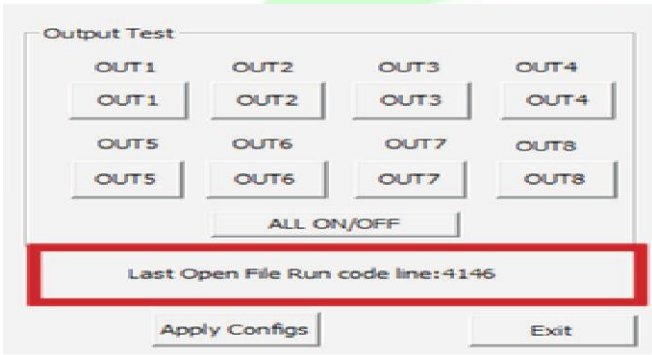
NO.5: Input Io: 16 Input port;In⁺ to In⁺.Active Low



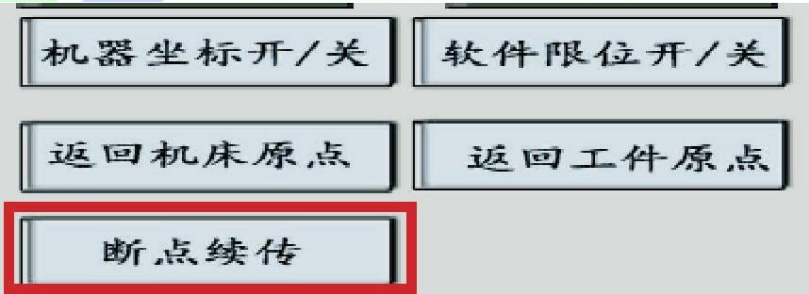
New Function

G-code line quantity save function

When our control card suddenly power off, the control card chip automatically save the current G code line number. Control card plug-in display save the number of lines.

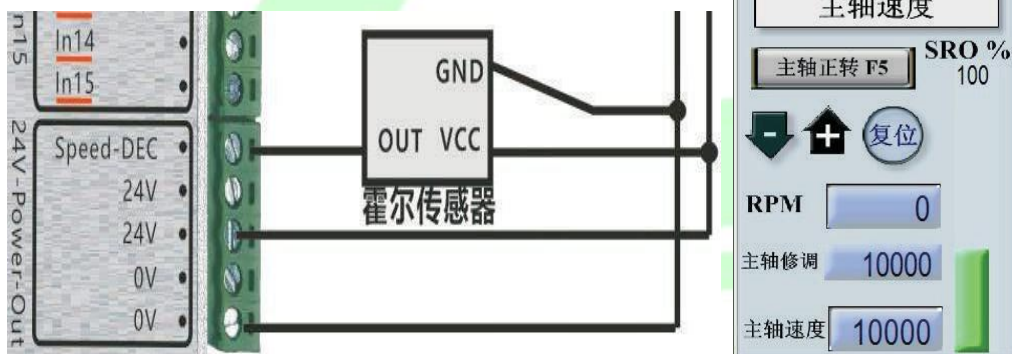


Wait until the control card is connected to the power supply next, load the G code program, click the power to continue to the break continue button, Mach software automatically from the last save the number of lines to start running.



Spindle speed feedback

Current Spindle rotary speed send to our card port "Speed-DEC", then display RPM speed on Mach3. Maximum support feedback input Pulse frequency 20KHZ.

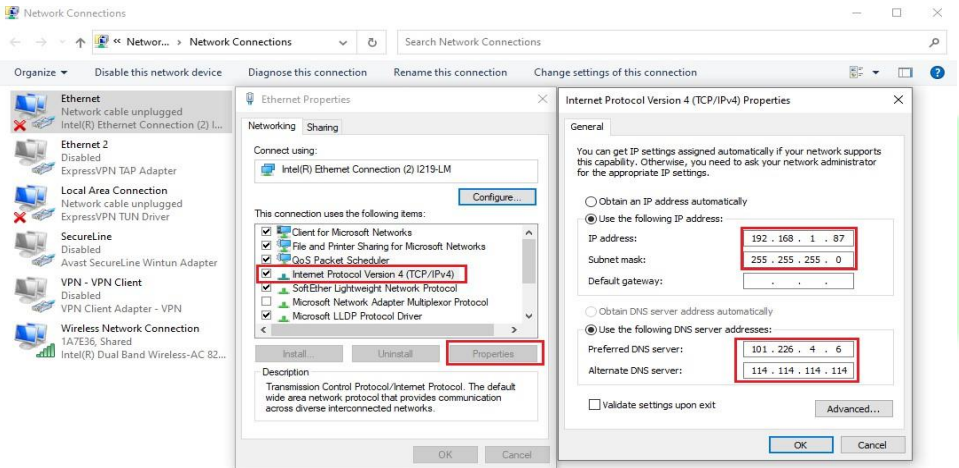


First step: the computer IP address setting.

<Ethernet card directly connected to the computer> Please open "network sharing center", select the "local connection - property", open "Internet protocol version 4 (TCP/IPv4)", and manual input IP address 192.168.1.xx (XX from 2-179, can not be repeated)

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New Function



Ethernet card connected to the router

If your Ethernet card is connected to your computer via a router, Please make sure your router IP address format is 192.168.1.xx , If not, modify your router IP address into 192.168.1.xx format. Otherwise unable to communicate. Modify the IP address of the router, and then manually set the IP address of the computer in accordance with the above method.

The second step: Ethernet card Mach™ software IP address Setting

After PC IP address is set up, open the Mach™ software "plug-in control" in the figure below the location of the choice of a IP address, range: 180-190. (If you have only one set of control card, skip this setting. Factory defaults IP: 180)

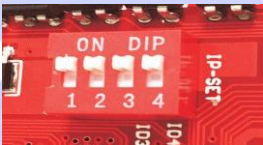
Please input the connect card IP address

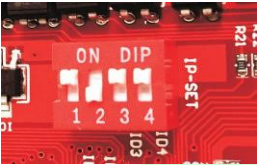
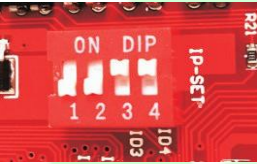
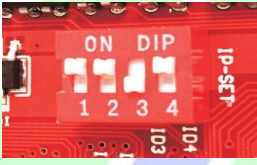
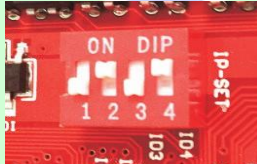
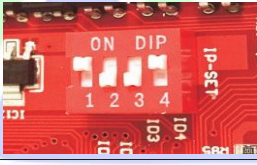
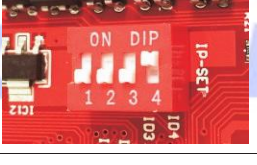
The Card IP: 192.168.1.

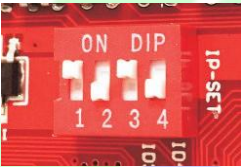
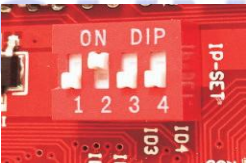
Please make sure your computer is in the same domain with the xhc ethernet card!

The third step: IP internal Ethernet switch setting

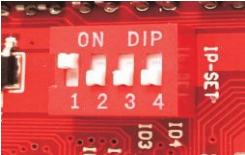
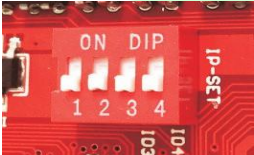
if you only connected with 1 set of our Ethernet control card, skip the step. IP factory default is 180. open Ethernet control card control card circuit board in the shell, the upper inner has a red dial switch, a total of 4 of them. You can set the IP, range: 180-183, corresponding to the IP address of the Mach3 software plug-in control: 180-183. default all dial switch goes to the ON position, IP address is 180, corresponding to Ethernet IP of Mach3 software: 180. Refer to the following table settings:

Dial switch setting	Mach3 software IP
	IP: 180
	IP: 181

Dial switch setting	Mach software IP
	IP: 182
	IP: 183
	IP: 184
	IP: 185
	IP: 186
	IP: 187

Dial switch setting	Mach3 software IP
	IP: 188
	IP: 189
	IP: 190
	IP: 191
	IP: 192
	IP: 193

New Function

Dial switch setting	Mach3 software IP
	IP: 194
	IP: 190



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